PyCATSHOO

Addressing critical dependencies in the Probabilistic Performance **Assessments of multi-purpose systems with PyCATSHOO**



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PPA OF INTER-DEPENDENT SYSTEMS

DEPENDENCY TYPES

- Type 1
- Type 2
- Type 3

Type 4

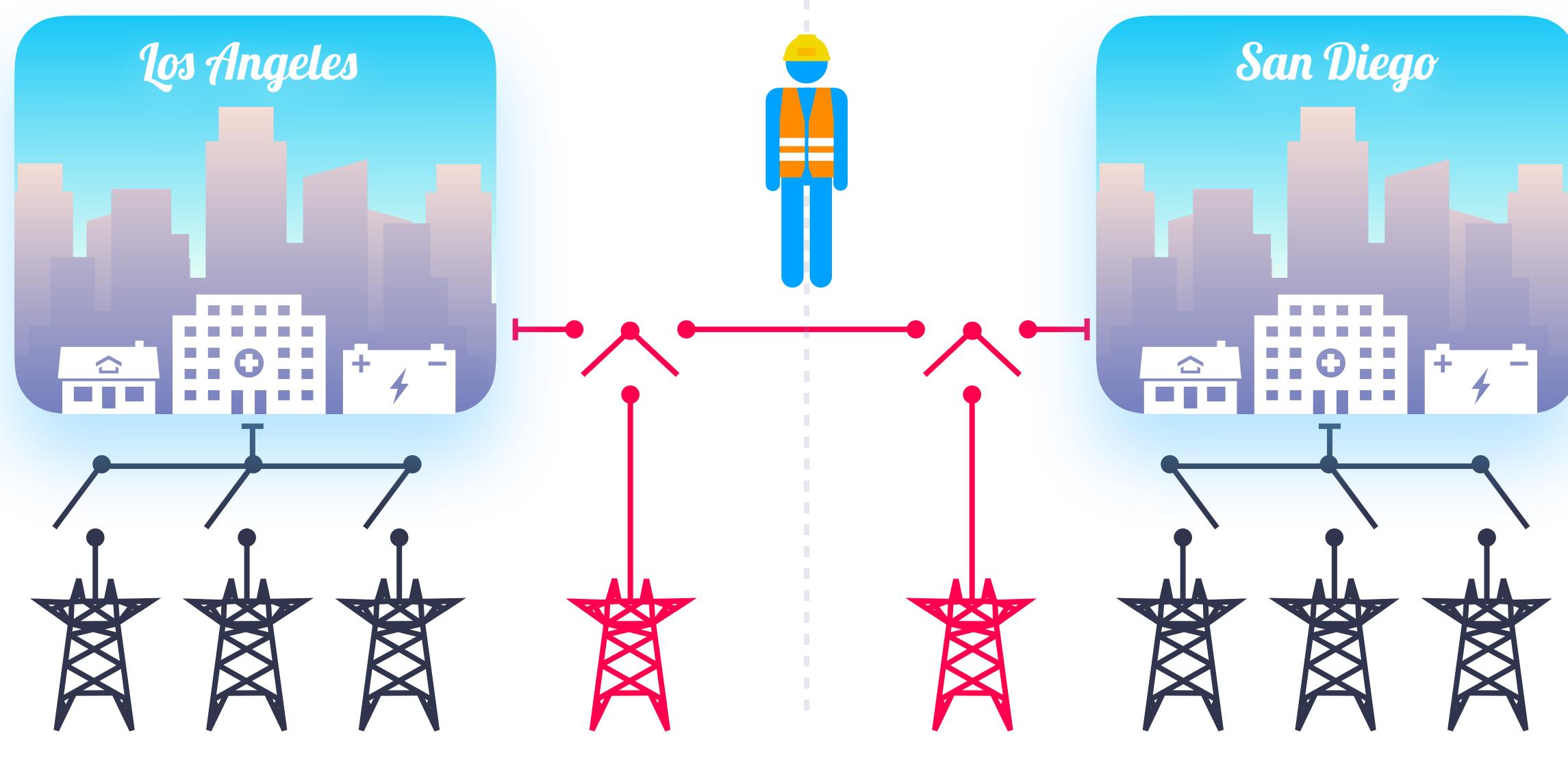
Type 5

Type 6

- A device usage shared between multiple areas and assigned to one of them according to a priority criteria which evolves over time.
- A human action shared between the same kind of activities in two different areas with different priorities which evolve over time.
- A human action shared between two kinds of activities with different but predefined priorities.
- An action which duration depends on a severity measure of the operating context.
- An action which failure probability depends on a severity measure of the operating context.

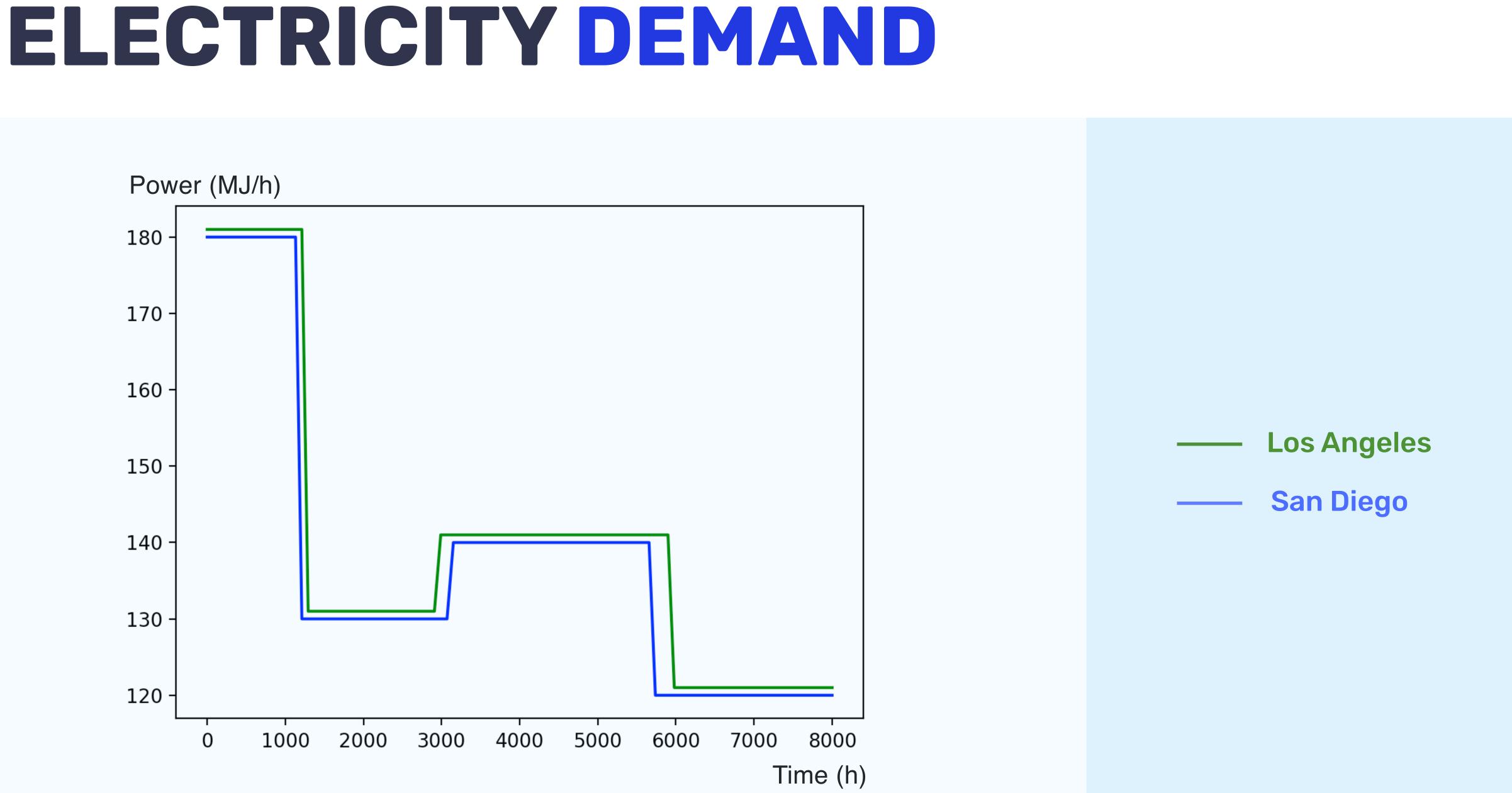
A device started/stopped according to the physical state of the system.



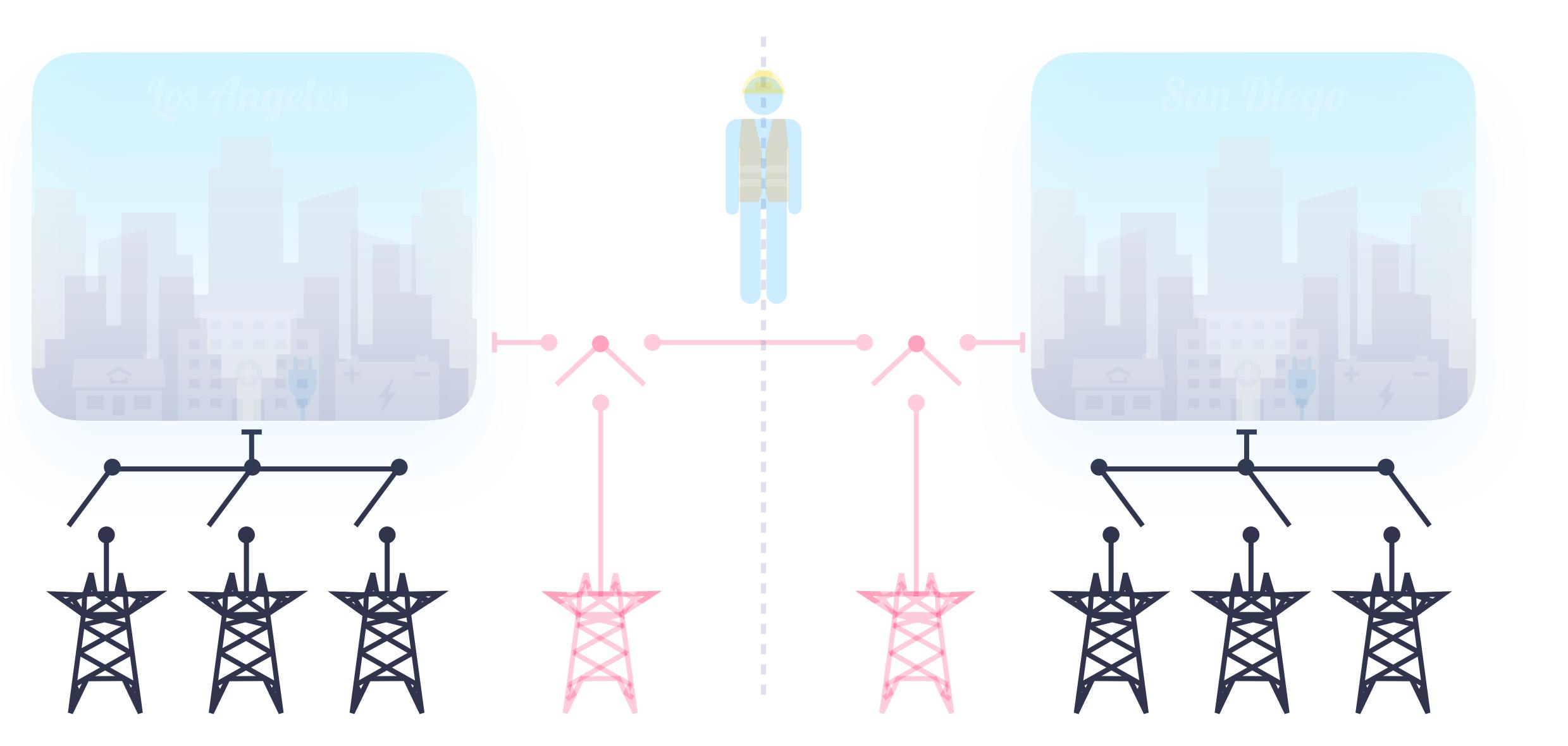




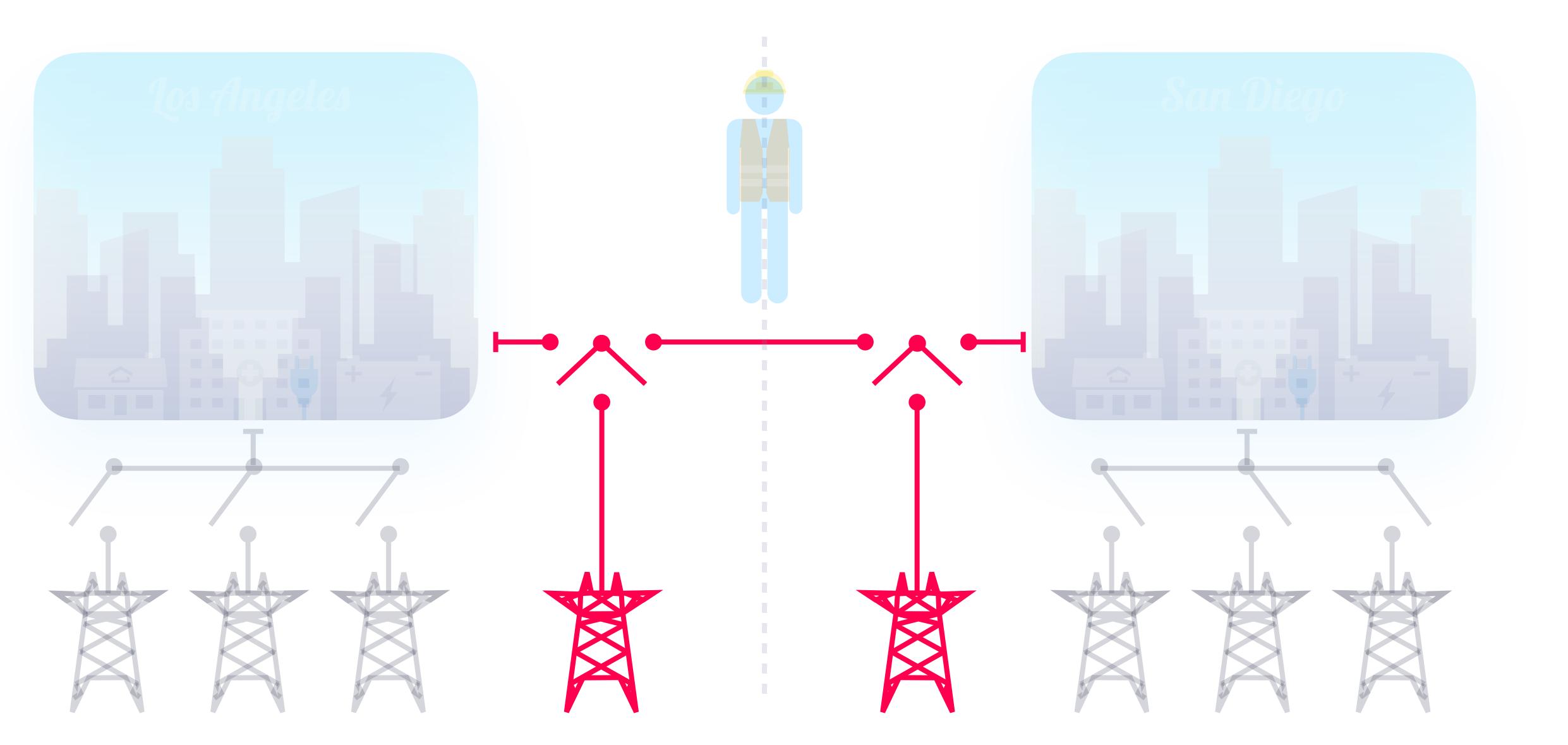




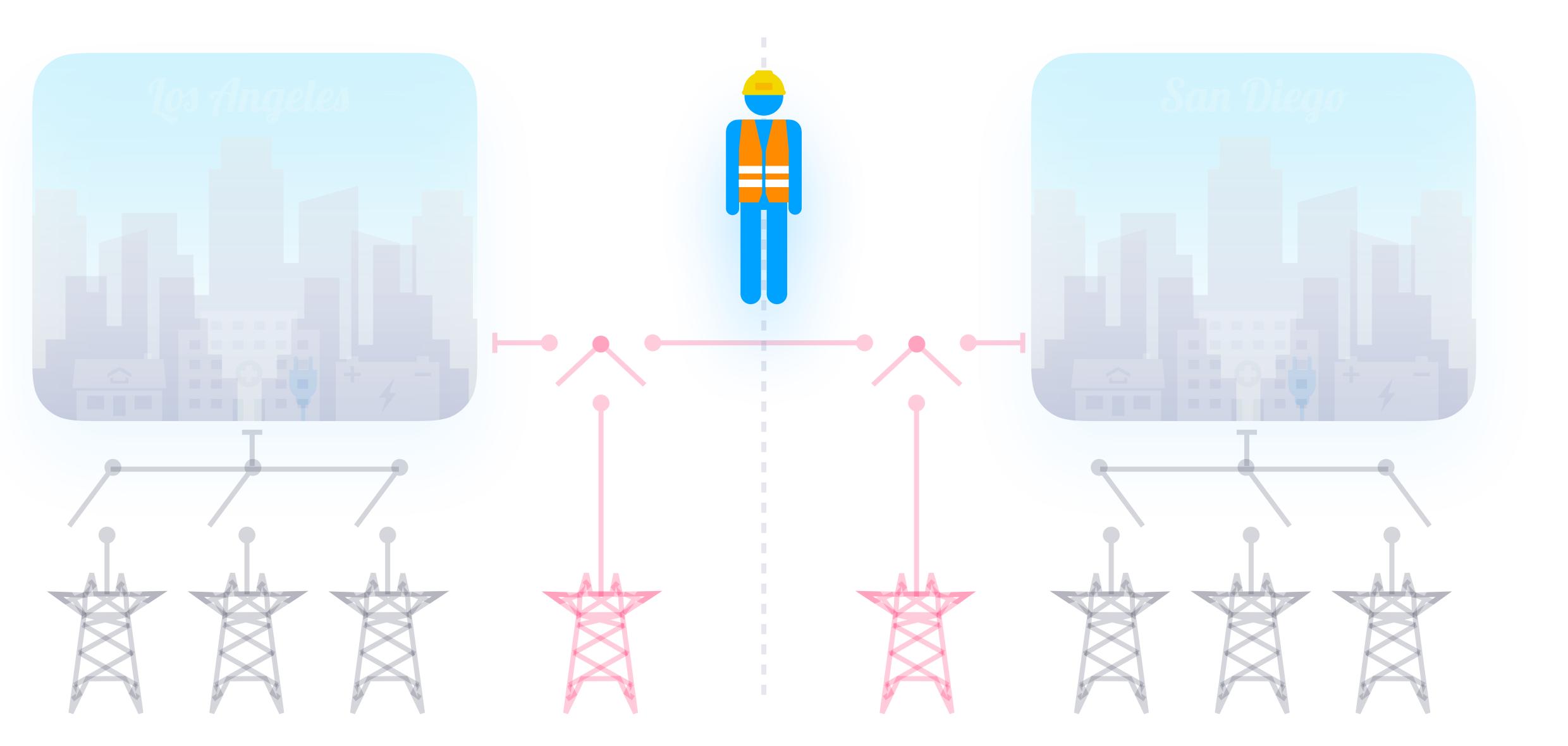














Pycatshoo Hybrid Modelling

CONTINUOUS AND DETERMINISTIC PHYSICAL PHENOMENA

DISCRETE STOCHASTIC EVENTS

SYSTEM MODELLING VERIFICATION

PyCATSHO0 modelling paradigms

Generic Modelling

System Modelling



For every kind of dependency

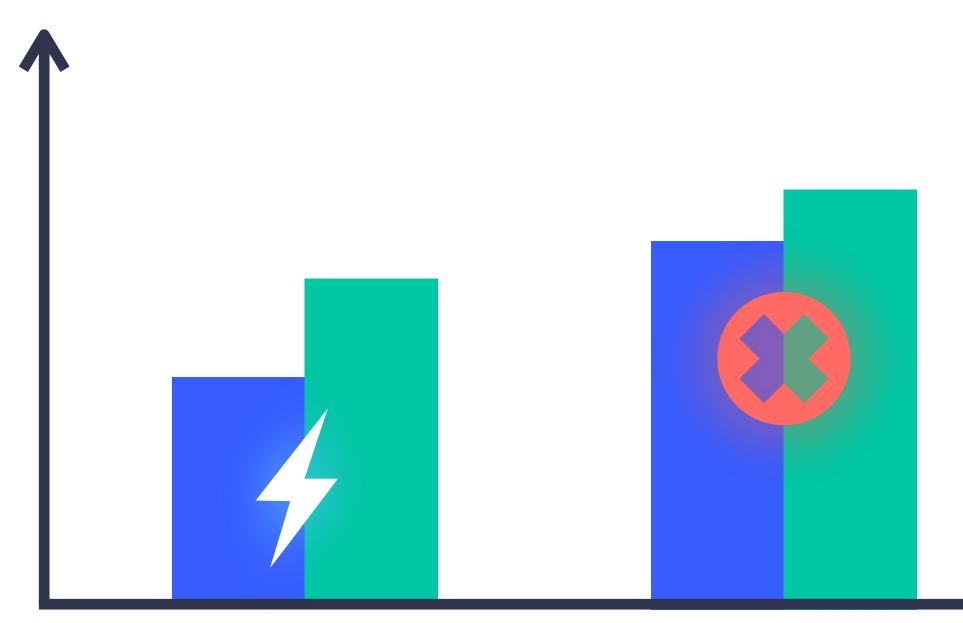
Simulations of specific scenarios

Modelling Validation



RESULTS OF THE PPA

Separated **Electricity Supply**



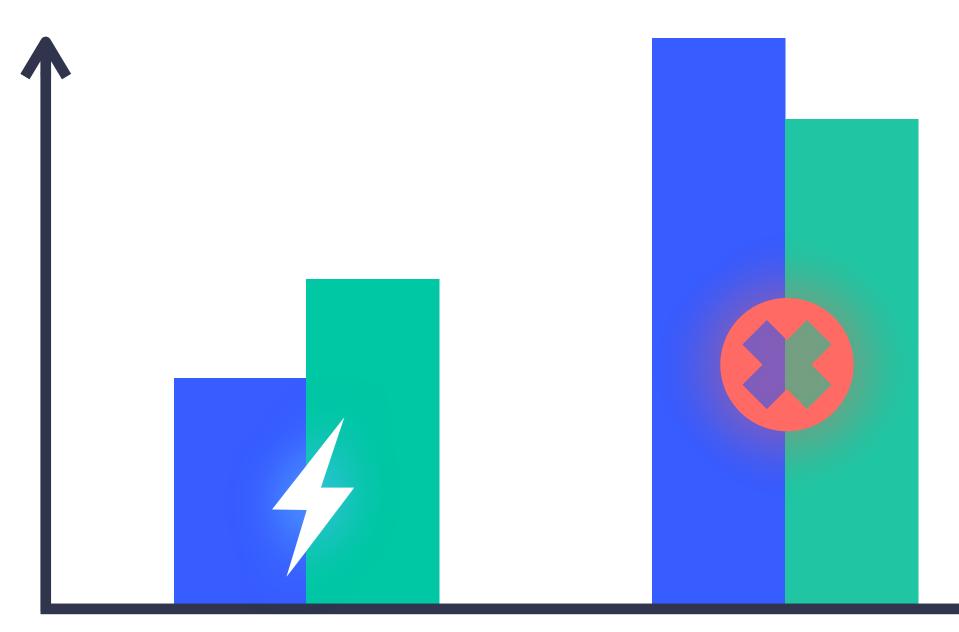
Electricity Load

Shortage **Probability**





Common **Electricity Supply**



Electricity Load

Shortage **Probability**



INTRODUCTION TOPYCATSHOO

MODELLING

BUILDING A MODEL LIBRARY OF GENERIC COMPONENTS



MODELLING A SPECIFIC SYSTEMS





BUILDING A MODEL LIBRARY OF GENERIC COMPONENTS

msgBox1

press_channel inFlow_channel

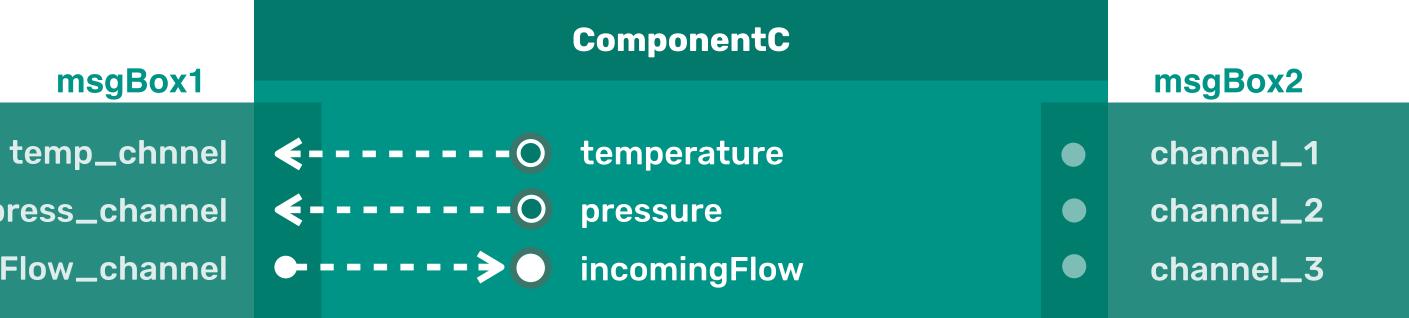
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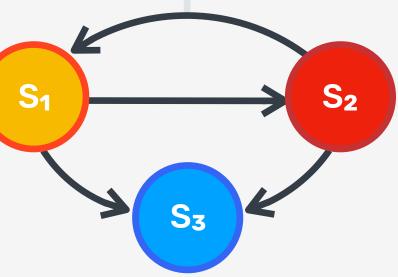
ODE: SLE: MILP:



Reference to a Stimulus \mathbf{O} from the external world



Transition: T>10°C | Exp(λ)



$$\frac{dX}{dt} = f(X, t)$$

$$A \cdot X = B$$

 $C^T X$ maximize $A'x \le B'$ such that

Sensitive methods

References: new values

SLE: MILP: **Transitions:** firing

ODE:

Triggers the execution of user defined actions

$$\frac{dX}{dt} = f(X, t)$$
$$A \cdot X = B$$

 $C^T X$ maximize $A'x \leq B'$ such that

Sensitive methods

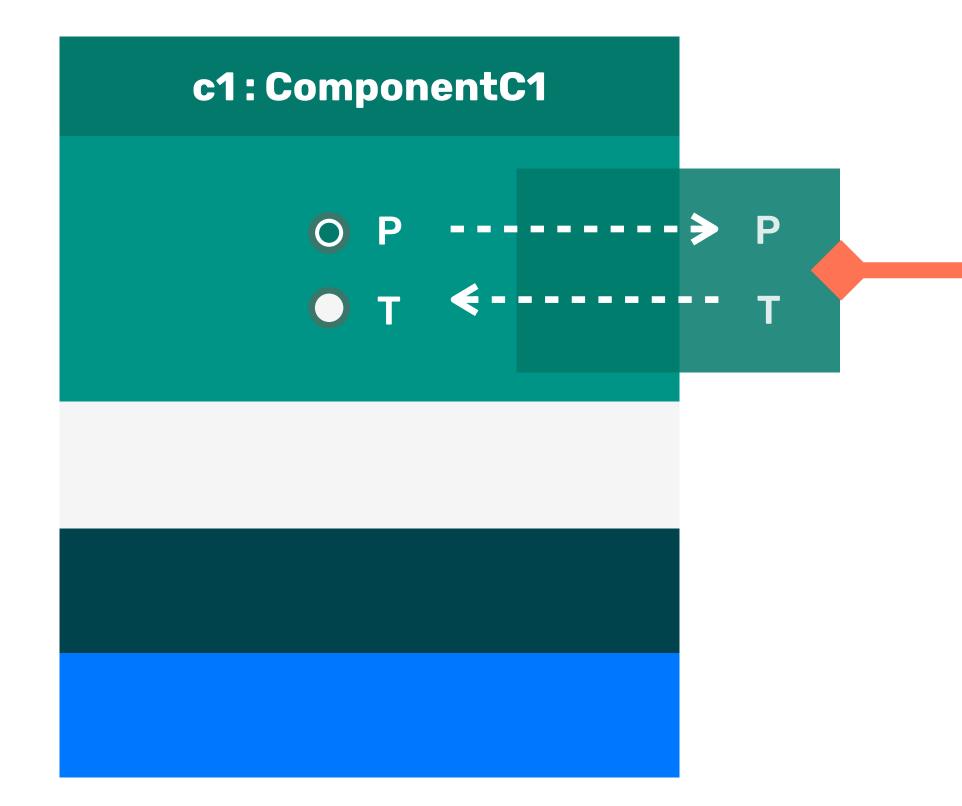
- **References:** new values

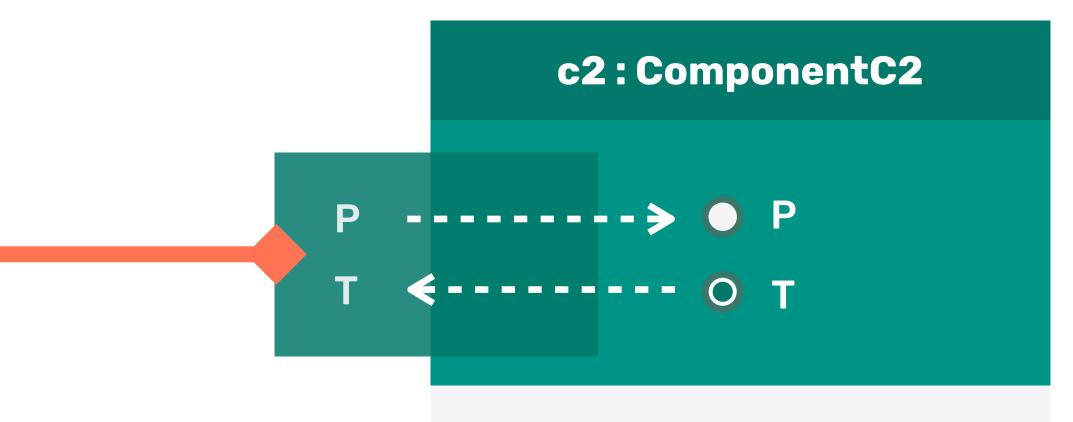
 - State: in / out
- Automata: transition between states
- Simulation: starting

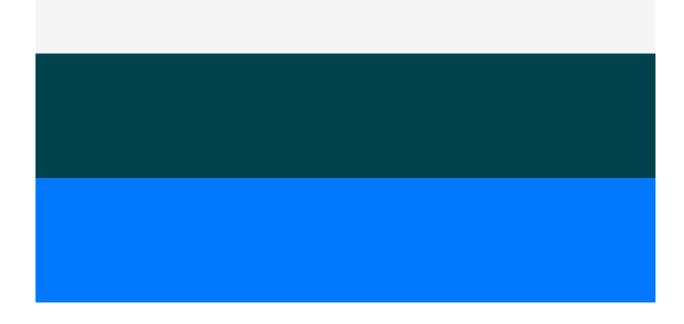


MODELLING **A SPECIFIC** SYSTEM

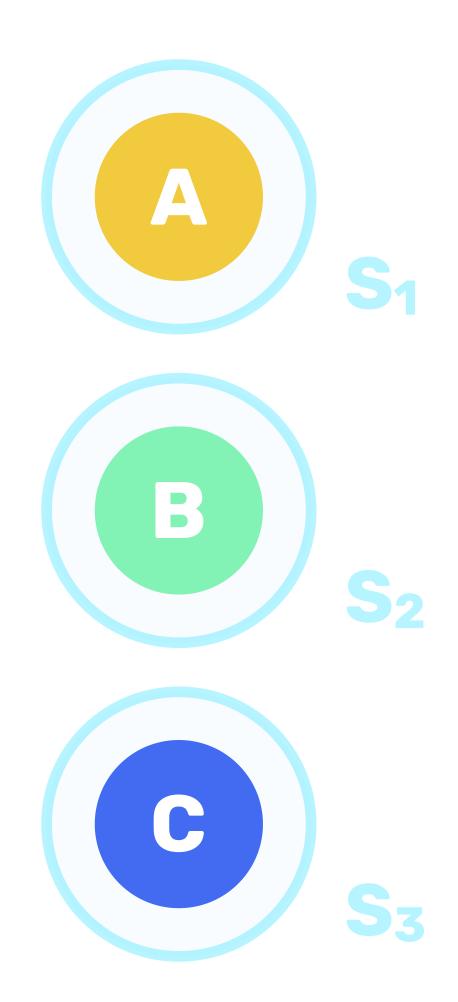
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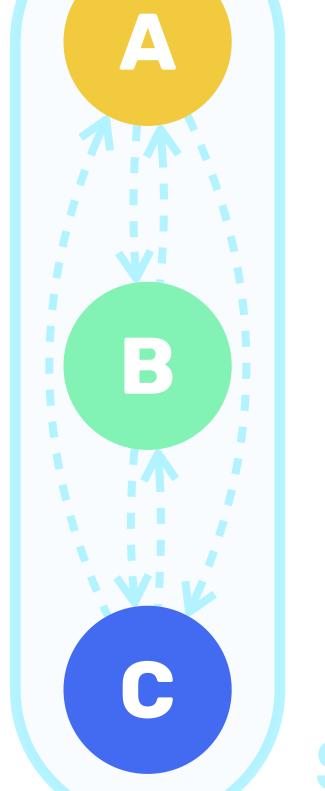








CONLUSION



- **S'**





Thank you for your attention

