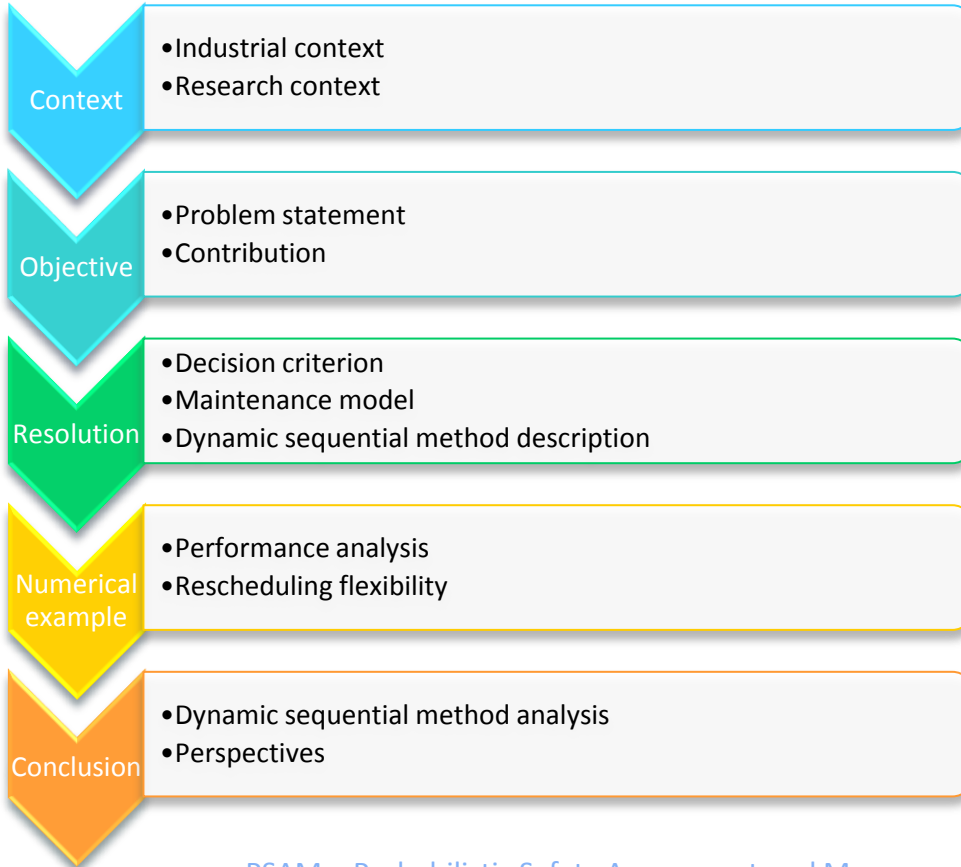


# Dynamic sequential decision making for missions and maintenance scheduling for a deteriorating vehicle

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# Agenda



# Industrial context

Why dynamically scheduling both missions and maintenance operations for a truck ?

Ensure the vehicle availability

Avoid unplanned stops

Fit to the vehicle usage

Schedule at best maintenance time slots

Adapt to the missions constraints

Adapt to disruptions

Improve productivity



# Research context

## Rescheduling environments

Static

Dynamic

Deterministic

Stochastic

No arrival  
variability

Arrival  
variability

Process flow  
variability

## Rescheduling strategies

Dynamic

Predictive-reactive

Dispatching  
rules

Control-  
theoretic

Periodic  
rescheduling

Event-driven  
rescheduling

Hybrid  
rescheduling

## Rescheduling methods

Schedule  
generation

Schedule repair

Nominal  
schedules

Robust  
schedules

Right-shift  
rescheduling

Partial  
rescheduling

Complete  
regeneration

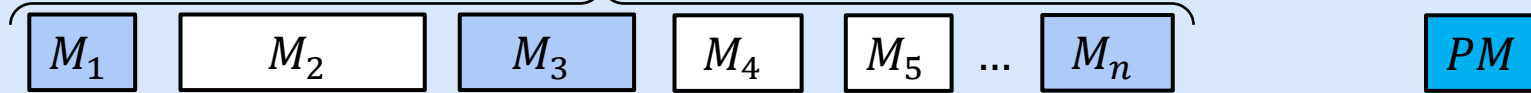


# Problem statement

## Activities

Initial missions set

Preventive maintenance



## Problem

$$\max_{\pi} G(\pi) \text{ s.t. } \forall k \in \llbracket 1; N_b \rrbracket, \mathbb{P}_f(k) \leq \mathbb{P}_{max}$$

Operating incomes

Schedule

Number of blocks composing  $\pi$

Probability to have one failure in block  $k$

Maximum failure probability

## Schedule

Initial schedule:

$(M_2, M_1)(M_5, M_4, M_n) \dots (M_3)$



Information during/ after  $M_x$ ?



$M_{n+1}$

Information type:

- Deterioration measurement
- Failure
- New mission(s)

Schedule update

Current schedule kept



# Contributions

- **Propose a predictive-reactive approach to jointly schedule missions and maintenance operations**
  - Generation of a schedule evolving over time according to monitoring information and disruptions
  - Maintenance model based on the vehicle deterioration evolution
- **Implement the rescheduling strategy based on a genetic algorithm**
  - Optimization criterion
  - Sequential rescheduling according to the event
- **Comparison between a static scheduling method and the dynamic one**
  - Performance analysis
  - Effect of the rescheduling



# Decision criterion

➤ Dynamic scheduling decision criterion:  $C(\pi) = G_m - C_d - C_m$

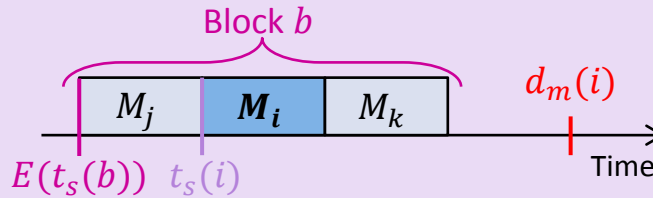
Gains earned when the missions are completed

$$G_m = \sum_{i=1}^n g_m(i)$$

$g_m(i)$ : gain generated by the mission  $i$

Delay costs

$$C_d = \sum_{i=1}^n c_d(i)$$



For  $M_i$ :  $c_d(i) = t_d(i)C_{ud}$   
with  $t_d(i) = t_s(i) - d_m(i)$

$E(t_s(b))$

$c_d(i)$ : delay cost for mission  $i$   
 $t_d(i)$ : delay time for mission  $i$   
 $E(t_s(b))$ : average beginning time for block  $b$

Maintenance cost

$$C_m = \sum_{b=1}^{N_b} \left( C_0 + C_f \sum_{k=1}^{N_f(b)} \mathbb{P}_f(b, k) \right)$$

$N_b$ : number of blocks  
 $C_0$ : preventive maintenance cost  
 $C_f$ : corrective maintenance cost  
 $N_f(b)$ : maximum number of considered failures for block  $b$   
 $\mathbb{P}_f(b, k)$ : probability to exceed the failure threshold  $L$  for the  $k^{th}$  time in block  $b$

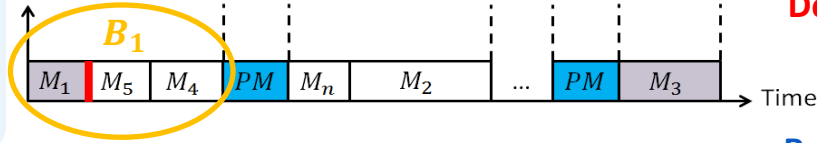
# Maintenance model

➤ **Deterioration-threshold failure model** → estimate the maintenance costs associated with failures

Gamma process:  $X \sim Ga(\alpha_i, \beta_i)$

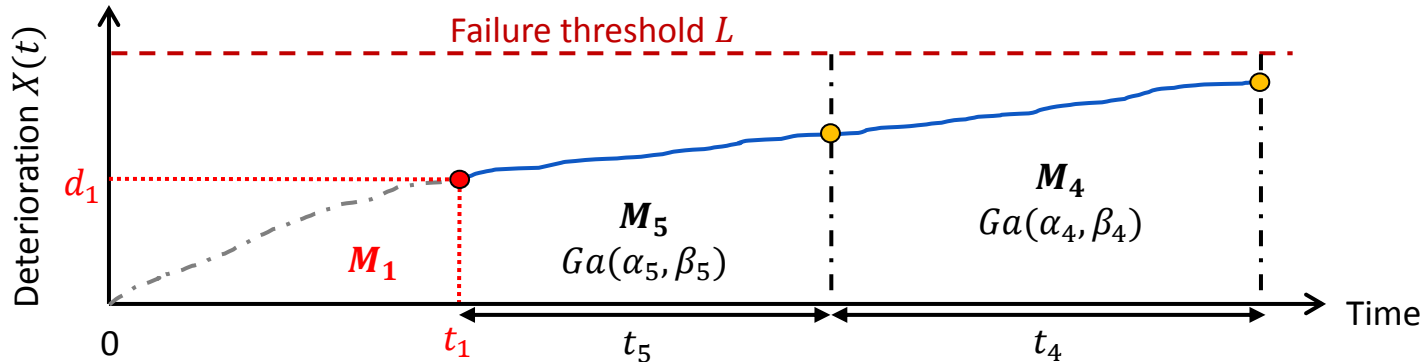
$X(t_d) = L \rightarrow$  failure

Mission



Deterioration level after  $M_1$ :  $d_1$

Remaining missions in  $B_1$ :  $M_5, M_4$

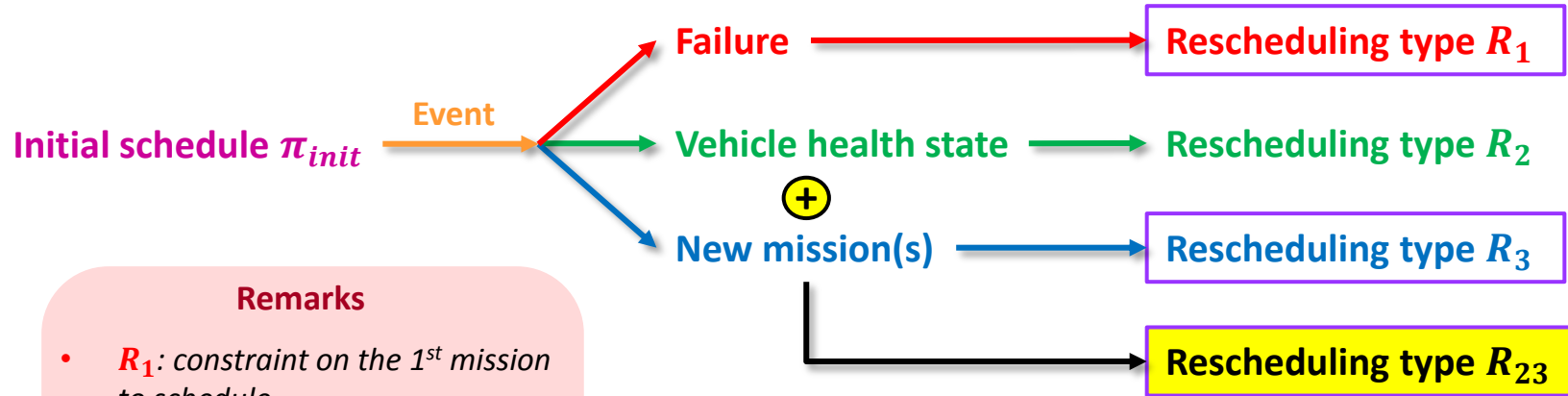


Equivalent Gamma process with the remaining missions → estimate the probability to exceed the threshold  $L - d_1$



# Dynamic sequential method

Based on a **genetic algorithm**

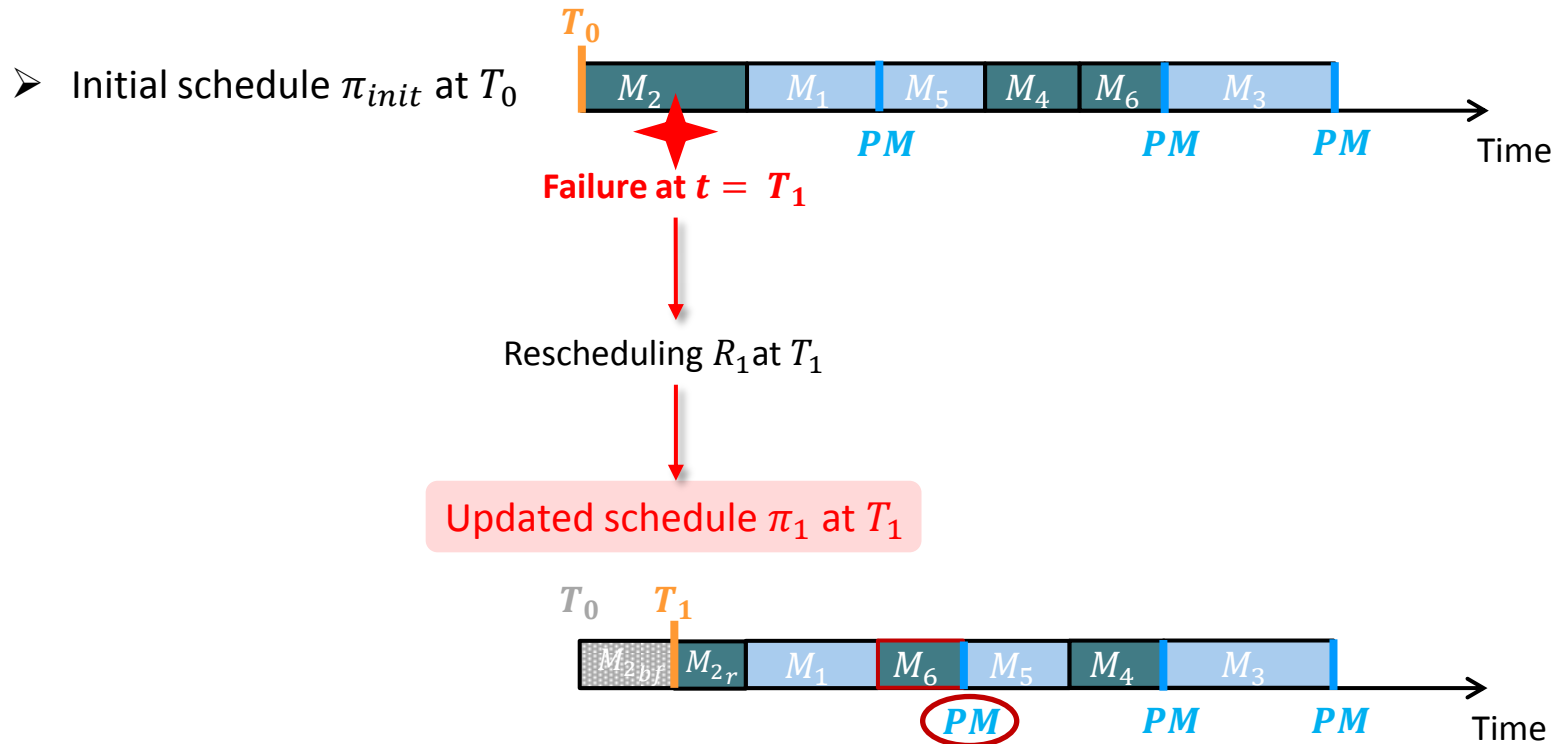


## Remarks

- $R_1$ : constraint on the 1<sup>st</sup> mission to schedule
- $R_2$ : constraint on the 1<sup>st</sup> mission block to fill in
- $R_3$ : add new missions in the missions batch

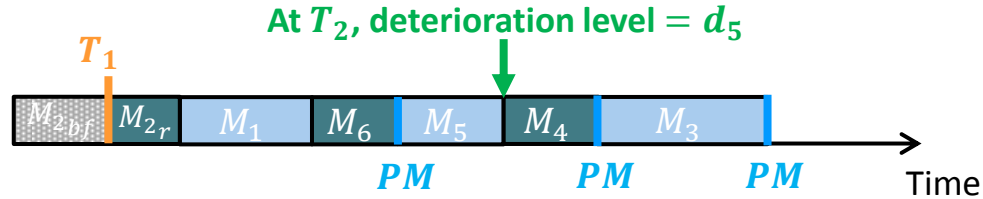
Mandatory rescheduling

# Dynamic sequential method

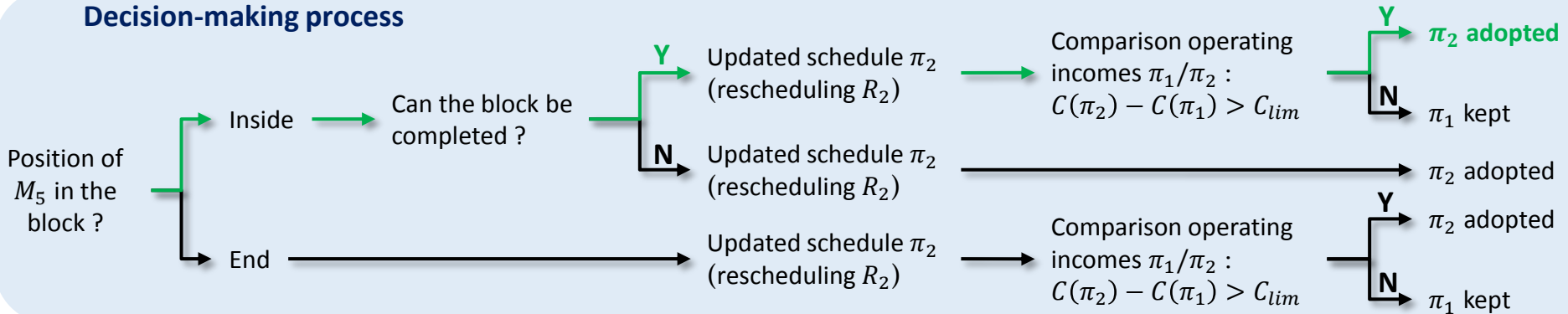


# Dynamic sequential method

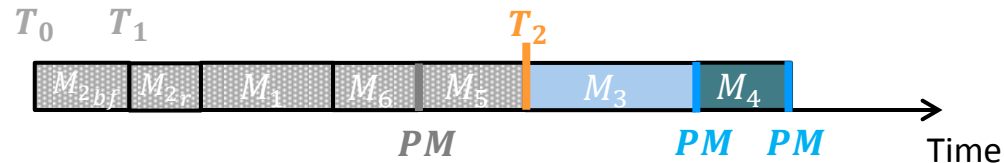
➤ Schedule  $\pi_1$  at  $T_1$



## Decision-making process



Updated schedule  $\pi_2$  at  $T_2$



# Numerical example: framework

Mission  $\rightarrow (t_m, \alpha_m, \beta_m, \mathbb{P}_m, g_m, d_m)$

$$\forall m, g_m = 5000$$

18 missions  $\rightarrow$  6 available at  $T_0$

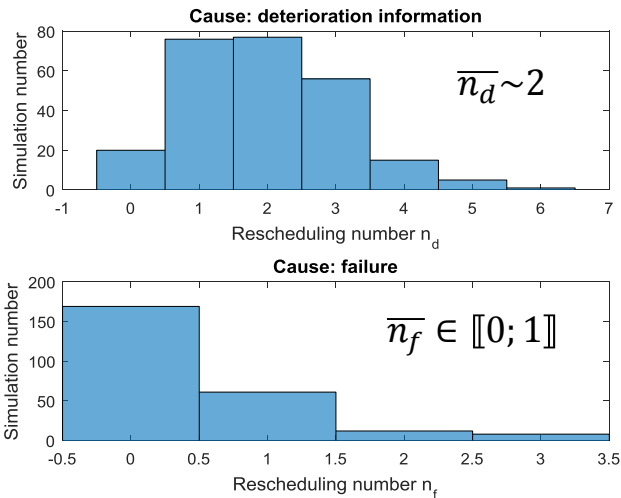
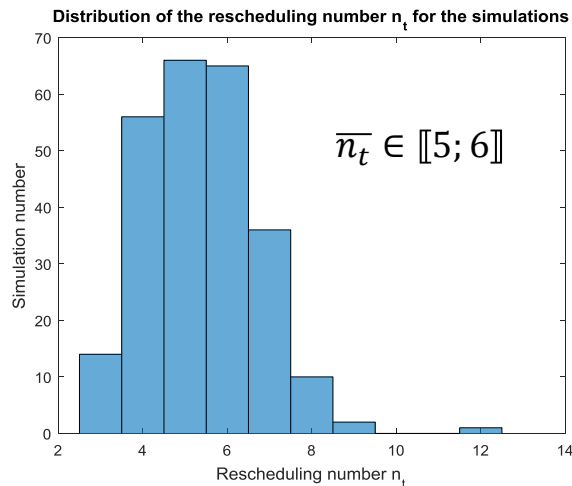
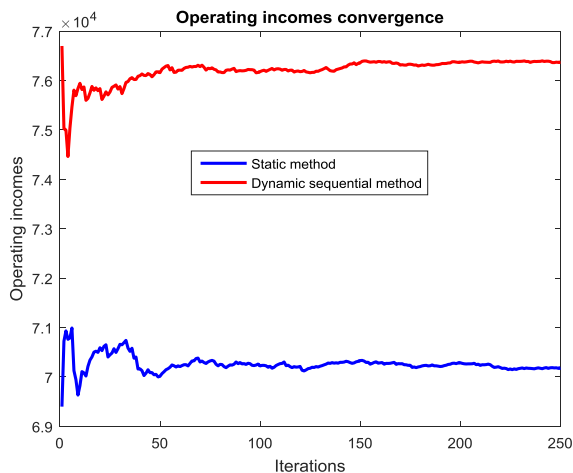
- $t_m$ : duration
- $(\alpha_m, \beta_m)$ : deterioration process parameters
- $\mathbb{P}_m$ : failure probability
- $g_m$ : gain
- $d_m$ : starting deadline

Parameters	Values
$C_{ud}$ : unitary penalty cost for delay	50
$C_0$ : preventive maintenance cost	1000
$d_p$ : preventive maintenance duration	2
$C_f$ : corrective maintenance cost	3000
$d_c$ : corrective maintenance duration	4
$L$ : failure threshold	100%
$\mathbb{P}_{max}$ : maximum failure probability	0.1

## Scenario

- **New missions:** 4 missions added after missions 1,3,5
- **Deterioration measures:** after missions 1,2,5,6,8,10,12,13,14,17,18
- **Monte-Carlo simulations**
- **Comparison** dynamic sequential method VS “static” scheduling method

# Performance analysis



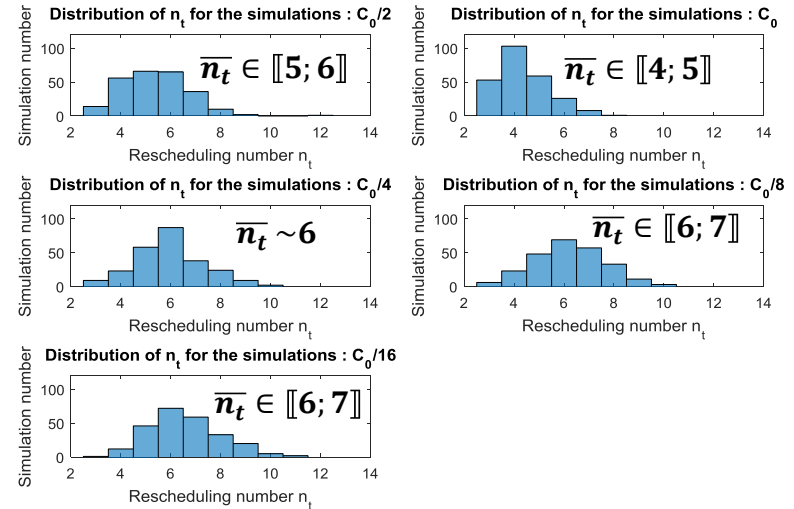
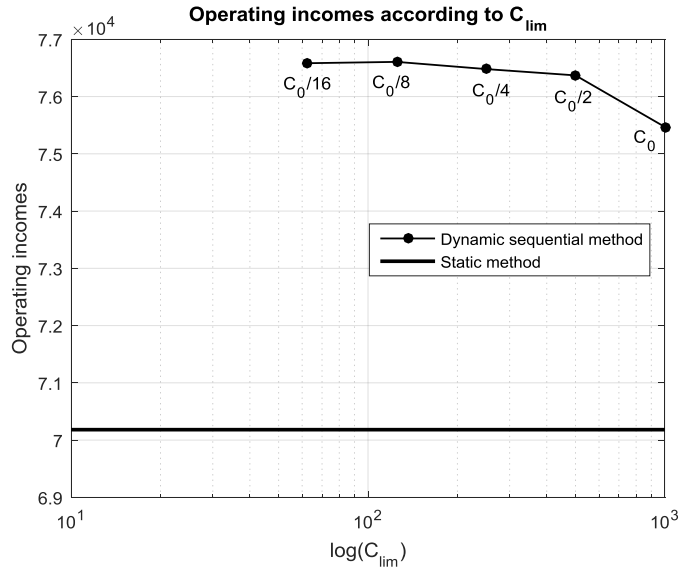
Method	Dynamic sequential	Static
Operating incomes	76370	70180
Number of blocks	9	13
Computation time	50s	10s

$$n_t = n_f + n_d + \underbrace{n_m}_{=1} + \underbrace{n_{md}}_{=2}$$

**Monitoring information → Rescheduling → Benefits generated by the dynamic sequential ~8,8%**

# Rescheduling flexibility

When vehicle health state available → Rescheduling limit condition  $C_{lim}$



Rescheduling effect in the operating incomes through the delay costs to limit disruptions

# Conclusion

- **Predictive-reactive rescheduling strategy to schedule missions and maintenance operations**
  - Schedule evolving over time according to available monitoring information
  - Maintenance model based on deterioration-threshold failure model
- **Decision-making process**
  - Optimization criterion → balance between the gains, the delay costs and the maintenance costs
- **Comparison dynamic sequential and “static” methods**
  - Increase of the operating incomes ~8.8% at the expense of the computation time
  - Better fit to the vehicle health state
  - Rescheduling limit condition → avoid too many rescheduling



The cost necessary to retrieve the monitoring information is not considered

Next step: Develop a similar method for a fleet of vehicles



**Thank you for your attention.**



**Questions ?**