

HRA Data for Performance Shaping Fact ors Reflecting Digital MCR

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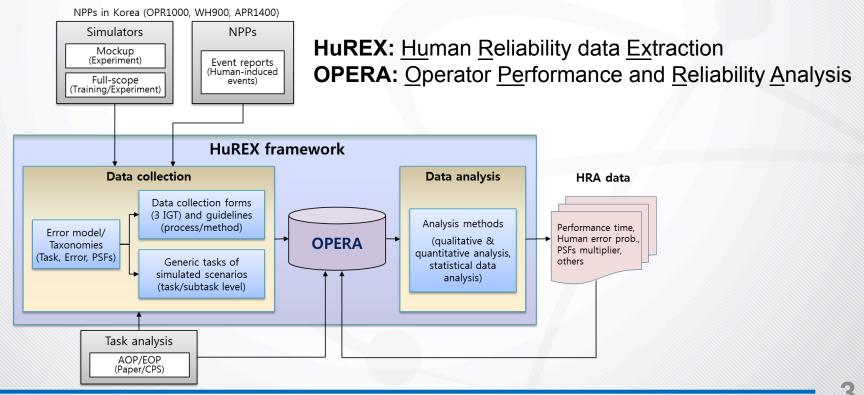
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- Characteristics of Digital MCR
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HuREX (Human Reliability data EXtraction)

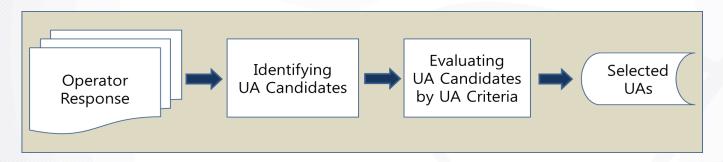
- **KAERI's project to** generate HEP (human error probability) data using 0 a framework for HRA data collection
 - HuREX framework including the detailed guidelines of HRA data collection was established
 - Data collection with simulator training data has been performed to identify UA (Unsafe Act)
 - HRA data was extracted by the HuREX from the full-scope simulator records



Unsafe Act (UA) Identification

UA definition

- UA is an inappropriate operator behavior that has a potential for leading the safety of N PPs toward a negative direction
- UA identification process



UA candidate: All kinds of deviations from the following procedure (AOP/EOP)

UA selection criteria

- Inappropriate manipulation or manipulation omission
- Inappropriate notification or notification omission
- Inappropriate procedure progression (procedure or step)

AOP: Abnormal Operating Procedure / EOP: Emergency Operating Procedure ightarrow

Data Fields of IGTs (Information Gathering Templates) Overview IGT Response IGT UA IGT 1. UA Information 1. Plant/Simulation Overview Conducted Task Information 1. ٠ Time 2. UA Initiator 2. Crew Procedure / Step ٠ 3. Plant/System State Contents ٠ 3. Training & Education 4. Time Pressure Task Type ٠ 4. Environment Number of Demand ٠ 5. Task Familiarity Number of Success ٠ 5. Observed Response 6. Task Complexity (Decision-making) Operator ٠ Component Type ٠ 7. Task Complexity (Execution) 6. Scenario System Type ٠ 8. Procedure Quality (Clarity) 7. Crew characteristics & 2. UA Analysis 9. Procedure Quality (Description level) **Dynamics** UA Candidate 10. HMI Information Quality UA Code EOO / EOC 11. Communication Quality ٠

Description

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UA Type Classification

Cognitive activity	Task type	Abbreviation	Error mode [*]
	Checking discrete state - Verifying alarm occurrence ${\cal Y}$	IG-alarm♪	EOO, EOC♪
	Checking discrete state - Verifying state of indicator $ ho$	IG-indicator	EOO, EOC♪
	Checking discrete state - Synthetically verifying information $\!$	IG-synthesis♪	EOO, EOC♪
Information gathering and	Measuring parameter - Reading simple value	IG-value♪	EOO, EOC♪
reporting (IG)	Measuring parameter - Comparing parameter ${\cal Y}$	IG-comparison♪	EOO, EOC♪
	Measuring parameter - Comparing in graph constraint ${\cal Y}$	IG-graph♪	EOO, EOC⊅
	Measuring parameter - Comparing for abnormality	IG-abnormality	EOO, EOC⊅
	Measuring parameter - Evaluating trend	IG-trend♪	EOO, EOC♪
	Entering step in procedure $\!$	RP-entry♪ERP-procedure♪ERP-step♪ERP-information♪E	EOO♪
Response planning	Transferring procedure♪	RP-procedure	EOO, EOC♪
	Transferring step in procedure	RP-step♪	EOO, EOC♪
and instruction (RP)	Directing information gathering	RP-information	EOO, EOC♪
	Directing manipulation	RP-information♪ RP-manipulation♪ RP-notification♪	EOO, EOC♪
	Directing notification/request	RP-notification♪	EOO, EOC♪
	Diagnosing	SI-diagnosis	EOO, EOC♪
Situation interpreting (SI)	Identifying overall status)	SI-identification	EOO, EOC♪
	Predicting	SI-prediction	EOO, EOC♪
	Manipulation - Simple (discrete) control	IG-synthesisIG-valueIG-comparisonIG-comparisonIG-graphIG-graphIG-abnormalityIG-trendRP-entryRP-procedureRP-stepRP-informationRP-notificationSI-diagnosisSI-diagnosisSI-diagnosisSI-diagnosisSI-diagnosisSI-diagnosisSI-diagnosisSI-diagnosisSI-diagnosisSI-diagnosisSI-diagnosisSI-diagnosisSI-diagnosisSI-diagnosisSI-diagnosisSI-predictionSI-predictionEX-continuousEX-continuousCT-planningOT-manipulation	EOO, WDEV, WDIR♪
	Manipulation - Simple (continuous) control	EX-continuous♪	EOO, WDEV, WDIR, WQTY♪
Execution (EX)	Manipulation - Dynamic manipulation ${\cal N}$	EX-dynamic) EOO, WD	EOO, WDEV, WDIR, WQTY♪
	Notifying/requesting to MCR outside♪		EOO, EOC♪
	Unauthorized control - Unguided response planning and instruction	OT-planning,	EOC♪
Other (OT)	Unauthorized control - Unguided manipulation ${\cal Y}$	OT-manipulation♪	EOC⊅
	-♪		Timing error (too fast/too late)♪

*EOO (Error of Omission); EOC (Error of Commission); WDEV (Wrong Device); WDIR (Wrong Direction); WQTY (Wrong Quantity)

Expansion of the Study into Advanced MCR





Advanced MCR

HRA Data Analysis Reflecting Digital MCR Based on Hu REX Framework

 New research project to develop HEPs and extract HRA data using a simulator at the APR 1400 (Advanced Power Reactor 1400MWe),

The purpose of this paper

- To describe the characteristics in a digital MCR and operator behavior characteris tics of a digital environment from simulator data
- To develop HRA data items for UA IGT to reflect the characteristics of a digital MC R

Environment of Digital MCR

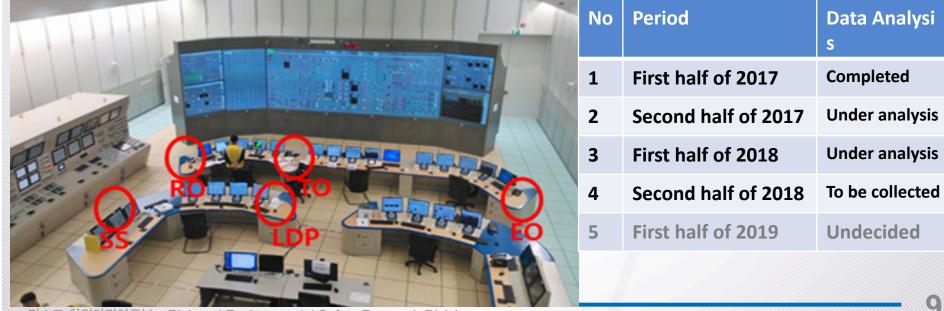
- <complex-block>
- Characteristics of digital MCR
 - IPS (Information Processing System)
 - LDPs (Large Display panels)
 - CPS (Computer-based Procedure System)
 - SCs (Soft Controls)

Data Collection & Analysis from APR1400 Simulator

From a full-scope simulator

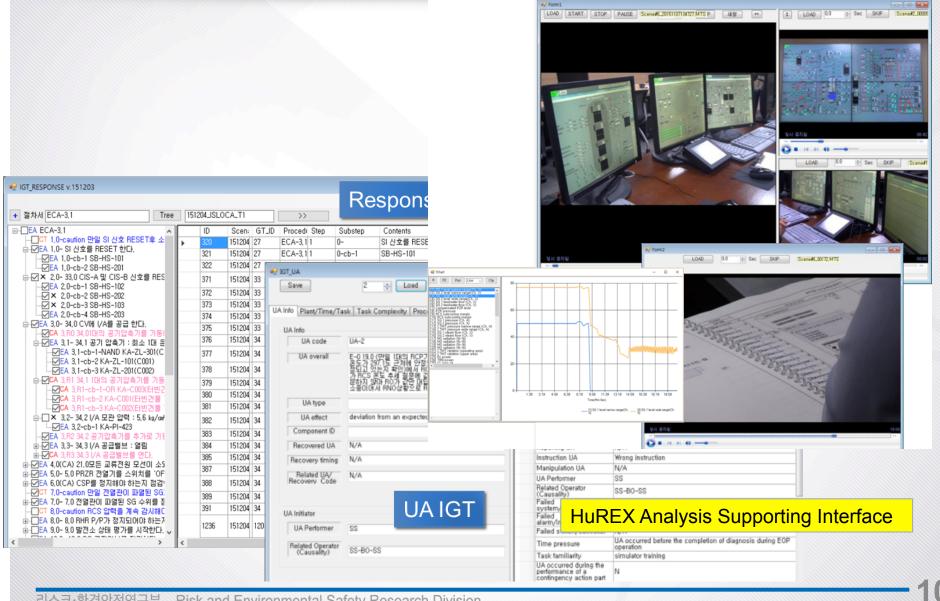
- Video/Audio recording data
 - Five cameras
- Data from questionnaires
 - Operator information
 - Operating culture

- Simulation log data
 - Process parameter log
 - CPS log
 - Alarm log
 - IPS screen navigation log



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HuREX Analysis Supporting Interface



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Characteristics of Operator' Behaviors in Digital MCR

Information gathering from a computer based information display system

- SS(shift supervisor)' checking/verifying the plant status by observing pro cess parameters and alarms on LDP or IPS
- Operator's clear measurement of process parameters on LDP and their t rends by using graphs on the operator console.
- Distributed placement of process variables/alarm

(The type of SS's information gathering, Information on LDP, The type of ala rm display)

Component manipulation with soft controllers

- Operator's screen navigation to find an appropriate screen for a compon ent manipulation
- Time delay in using soft controls due to significantly different types of de vices from the conventional MCR

(The type of control device for component manipulation, The number of scre en changes to the proper control device)

Characteristics of Operator' Behaviors in Digital MCR

Procedure operation with CPS

- Multiple operators' simultaneous checking/reviewing the other's procedur e operation (cross checking)
- One operator's multiple procedure operation at the same time
- Convenience due to CPS automation
 - Logic calculation
 - Highlighting
- Paper procedural operation in case of a CPS failure
 - Loss of automation provided by a CPS, such as logic processing and highlighting.

(Logic of the state identification or instructions, The procedure type , Hold step, The number of procedures performed at the same time , Design consistency of back up procedure, CPS-IPS direct link, CPS automation level)

HRA Data Reflecting Digital Environment for UA IGT (1/2)

Category of UA IGT	HRA Data	HRA Data Attributes
Task complexit y (decision-ma king)	The type of SS's information gathering	 Independent confirmation w/o direction to BO Direction to BO Notification to BO after independent confirmation
	Logic of the state identification or instructions	- NOT ,- AND, - OR, - NOT & AND, - NOT & OR' - AND & OR - NOT & AND & OR - Simple Statement (No Logic)
Task complexit y (execution)	The procedure type	 Paper based procedure Computer based procedure Back up procedure
	The type of control device for component manipulation	 Conventional device Mouse (non-safety) Mouse+ESCM (safety) Device on safety console
	The number of screen changes to the proper control device	- 0, 1, 2, 3
	Hold step	- Y/N
	The number of procedures performed at the same time	- 0, 1, 2, 3

HRA Data Reflecting Digital environment for UA IGT (1/2)

Category of UA IGT	HRA Data	HRA Data Attributes
Procedure qual ity (Clarity)♪	Design consistency of back up procedure	- Y - N
HMI & Informa tion quality,	The type of alarm display	 Alarm on dedicated alarm (alarm tile) Alarm on process mimic display Alarm on alarm list only
	Information on LDP	- Y - N
	CPS-IPS direct link	- Y - N
	CPS automation level	 - 1 (Manual Operation) - 2 (Shared Operation) - 3 (Operation by Consent) - 4 (Operation by Exception) - 5 (Autonomous Operation)

CONCLUSION

In this paper,

- Operator behavior characteristics of a digital environment including t he design characteristics in digital MCR are described
- New 12 HRA data items based on the characteristics of a digital MC R, such as an IPS, LDP, CPS, and SCs are derived based on the op erator' behaviors found from the simulation data
- And the 12 HRA data are connected with the category of the existin g UA IGT for a conventional MCR

In a further analysis,

- We are to develop HEPs for an advanced MCR and identify the relation between UAs and PSFs
- We investigated more various HF issues through a literature survey and discussed additional HRA data items.
 - For example, several researches insisted on the issue of operator' fatigue owing to the digitalized device in a digital MCR
- We plan to continue to modify or add HRA data items through a furt her simulation data analysis

THANK YOU



Human Factor Issues in Digital MCR

Design Element	HF Issue		Description
Computer based information display system	Information Overload	• •	Overlapping windows Too much information Faster information than visual process of human
	Interface management tasks	•	Navigation task before the primary task Losing the information because of secondary task under workload condition
Computerized procedure	Team performance	•	Breakdown in communication between operators
	Situation awareness	•	Reliance on computerized procedures
	Level of automation Keyhole effect	•	Automation level The limitation of parallel processing
	CPS failure in complex situation	•	The conversion to paper procedures
Soft controller	Unintentional activation	•	Unintended activity
	Description errors	•	Error by ambiguous information
	Mode errors	•	Mode error
	Disordering the components of an action sequence	•	Skip, repetition, and reverse
	Capture error	•	Confusion with the task performed infrequently
	Loss of activation errors	•	Errors induced by the limited memory of operator